

Vlasov Eqn.  $\rightarrow$  char. orbits  
 $\rightarrow$   $\nabla_{\text{Rows}}$  eqns.

1.

I.) Orbital Mechanics  $\rightarrow$  Disk Potential  
A.) Epicyclic Approximation (Linear)

Have:

$\rightarrow$  disk galaxy

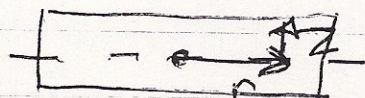
$\rightarrow$  cylindrical symmetry  $\Rightarrow V = V(r, z)$

Seek:

$\rightarrow$  basic characterization of stellar orbits  
in (a) azimuthally symmetric potential (e.g.  
equilibrium radius, small oscillation frequency,  
etc.)

$\rightarrow$  determine integrability vs. "approximate"  
integrability vs. stochasticity of orbits  
for different initial conditions

Now,



$$L = \frac{m}{2} (\dot{r}^2 + r^2 \dot{\phi}^2 + \dot{z}^2) - V(r, z)$$

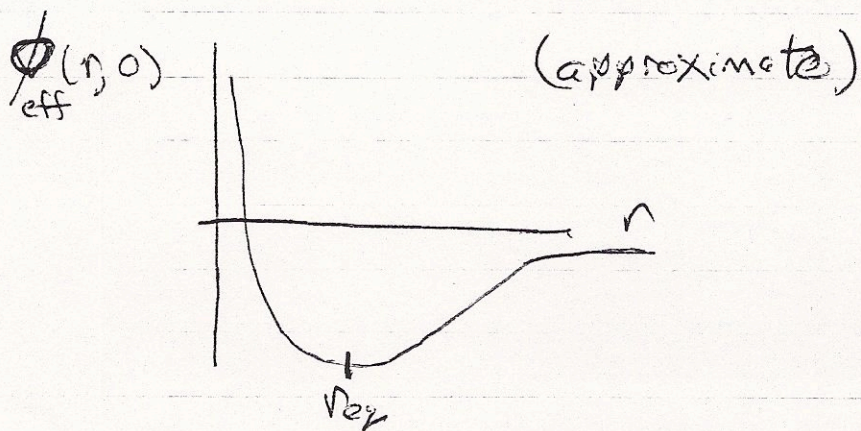
$$m\ddot{r} - mr\dot{\phi}^2 = -\frac{\partial V}{\partial r} \quad ; \quad m\ddot{z} = -\frac{\partial V}{\partial z}$$

$$\frac{d}{dt} (mr^2\dot{\phi}) = 0$$

$$\dot{\phi} = \frac{Lz}{mr^2}$$

$$\Rightarrow m\ddot{r} = mr \frac{Lz^2}{m^2 r^4} - \frac{\partial V}{\partial r} \quad ; \quad m\ddot{z} = -\frac{\partial V}{\partial z}$$

$$\equiv \frac{\partial}{\partial r} \left( \underbrace{V(r, z) + \frac{Lz^2}{2mr^2}}_{\text{effective potential}} \right) \equiv -\frac{\partial}{\partial r} \phi_{\text{eff}}$$



$\therefore$  first, seek expand about  $r=r_{cz}$ ,  $z=0$  (i.e.  $\frac{\partial V}{\partial z} = 0$ )

$$r_{cz} \Rightarrow \frac{\partial \phi_{\text{eff}}}{\partial r} = 0$$

at  $z=0$  by Gauss's law)

$$+ \frac{Lz^2}{mr^3} = \frac{\partial V}{\partial r} \Rightarrow \text{gives } r_{cz}$$

$\rightarrow$  "circular frequency"

observe:  $Lz = m r_{cz}^2 \Omega_c(r_{cz})$

$$\Omega_c^2(r_{cz}) = \frac{m r_{cz}^3}{m^2 r_{cz}^4} \frac{\partial V}{\partial r} \Big|_{r_{cz}, z=0}$$

"circular frequency"

∴  $\Omega_c^2 = \frac{1}{m r_{eq}} \left. \frac{\partial V}{\partial r} \right|_{r_{eq}, 0} \rightarrow$  defines circular frequency at  $r_{eq}$

Now, for small oscillations about  $r=r_{eq}, z=0$ ;  
ign. const.

$$\phi_{eff} = \phi_{eff}(r_{eq}, 0) + z \left. \frac{\partial \phi_{eff}}{\partial z} \right|_{r_{eq}, 0} + \frac{1}{2} (r - r_{eq})_{eff}^2 \left. \frac{\partial^2 \phi_{eff}}{\partial r^2} \right|_{r_{eq}, 0} + \frac{1}{2} z^2 \left. \frac{\partial^2 \phi_{eff}}{\partial z^2} \right|_{r_{eq}, 0} + \frac{\partial^2 \phi}{\partial r \partial z} \Big|_{r_{eq}, 0} (r - r_{eq}) z$$

$$\phi_{eff} = \frac{1}{2} x^2 \left. \frac{\partial^2 \phi_{eff}}{\partial r^2} \right|_{r_{eq}, 0} + \frac{1}{2} z^2 \left. \frac{\partial^2 \phi_{eff}}{\partial z^2} \right|_{r_{eq}, 0} \quad x \equiv r - r_{eq}$$

$$H = \frac{1}{2} m (\dot{x}^2 + \dot{z}^2) + \phi_{eff}(x, z) \rightarrow \text{harmonic oscillator}$$

$$= \frac{1}{2} m (\dot{x}^2 + \dot{z}^2) + \frac{1}{2} (x^2 \phi_{xx} + z^2 \phi_{zz})$$

key to all physics.

Now,  $\left. \frac{\partial^2 \phi_{eff}}{\partial r^2} \right|_{r_{eq}, z=0} = \left. \frac{\partial^2 V}{\partial r^2} \right|_{r_{eq}, z=0} + \frac{3 L_z^2}{2 m r_{eq}^4}$

but  $\left. \frac{\partial V}{\partial r} \right|_{r_{eq}} = \frac{L_z^2}{m r_{eq}^3}; \quad L_z = m r^2 \Omega_c$

$$\therefore \Omega_c^2 = \frac{1}{r} \frac{\partial V}{\partial r} = \frac{Lz^2}{r^4} \quad (m \rightarrow 1, \text{ as cancels})$$

$\Rightarrow$   
 $r, z$  oscillations:

i)  $\ddot{x} + K^2 x = 0$

$$K^2 = \left. \frac{\partial^2 V}{\partial r^2} \right|_{r_{eq}} + \frac{3Lz^2}{r_{eq}^4} = \left[ \frac{\partial}{\partial r} (r\Omega_c^2) + 3\Omega_c^2 \right]_{r_{eq}}$$

(hereafter drop 'sub-eq')

$$= \left( 4\Omega_c^2 + 2r \frac{\partial}{\partial r} \Omega_c^2 \right)_{r_{eq}, z=0}$$

$$= \frac{2\Omega_c}{r} \left. \frac{\partial}{\partial r} (r^3 \Omega_c) \right|_{r_{eq}}$$

and

ii)  $\ddot{z} + r^2 z = 0$

$$r^2 = \frac{\partial^2 \phi_{eff}}{\partial z^2}$$

Very  
important  
 $\downarrow$

Now

$$- \left\{ K^2 = 4\Omega_c^2 + 2r \frac{\partial}{\partial r} (\Omega_c^2) \right\}$$

$\rightarrow$  epicyclic frequency

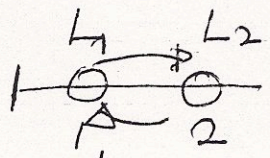
oscillation frequency } small radial excursions from  $r_{eq}$

observe  $R^2 = \frac{2\Omega}{r} \left( \frac{\partial}{\partial r} (r^2 \Omega) \right)$

↳ slope of angular momentum profile!

i.e.  $\begin{cases} \frac{\partial}{\partial r} (r^2 \Omega) > 0 \Rightarrow \text{stable (epicyclic oscillation) profiles.} \\ \frac{\partial}{\partial r} (r^2 \Omega) < 0 \Rightarrow \text{unstable (to epicycles) profiles.} \end{cases}$

i.e. consider  $\Delta E$  for interchange of 2 rings:



$E_{\text{before}} = \frac{L_1^2}{r_1^2} + \frac{L_2^2}{r_2^2}$

Rayleigh criterion

angular momentum conserved  $\rightarrow \begin{cases} m=0 \\ \text{rings} \end{cases}$

$E_{\text{after}} = \frac{L_2^2}{r_1^2} + \frac{L_1^2}{r_2^2}$

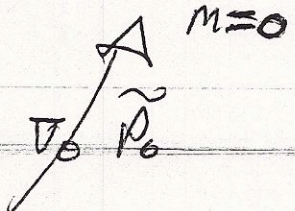
$\begin{cases} \Delta E > 0 \rightarrow \frac{\partial (r^2 \Omega)}{\partial r} > 0 \\ \Delta E < 0 \rightarrow \frac{\partial (r^2 \Omega)}{\partial r} < 0 \end{cases}$

- Continuum Picture  $\leftrightarrow$  Couette Flow ( $m=0$ )  
 ↳ cent. force

$\frac{\partial \tilde{v}_r}{\partial t} + \frac{\tilde{v}_\theta^2}{r} = -\frac{1}{\rho_0} \frac{\partial \tilde{p}}{\partial r}$

$\frac{\partial \tilde{v}_z}{\partial t} = -\frac{1}{\rho_0} \frac{\partial \tilde{p}}{\partial z}$

↳ Can / Does  $R^2$  (epi-freq) appear in continuum picture (i.e. rotating fluid)

$$\frac{\partial \tilde{V}_\theta}{\partial t} = -\frac{1}{r} \frac{\partial}{\partial r} (r^2 \Omega) \tilde{V}_r - \frac{1}{\rho} \nabla_\theta \tilde{\rho}_0$$


$$\nabla \cdot \underline{V} = 0$$

⇒ write  $\underline{V} = (\tilde{V}_r, \tilde{V}_z)$

$$\nabla \cdot \underline{V} = 0 \Rightarrow \underline{V} = \nabla \phi \times \hat{y}$$

$$\therefore V_r = -\partial_z \phi$$

$$V_z = \partial_r \phi$$

$$\underline{\omega} = \nabla \times \underline{V} ; \omega_y = -\partial_z^2 \phi - \partial_r^2 \phi = -\nabla_\perp^2 \phi$$

↑  
vorticity component  
in  $\hat{y}$  direction

So

$$\frac{\partial}{\partial t} (-\nabla_\perp^2 \tilde{\phi}) = -2\Omega \partial_z \tilde{V}_\theta$$

$$\frac{\partial \tilde{V}_\theta}{\partial t} = -\partial_z \tilde{\phi} \frac{1}{r} \frac{\partial}{\partial r} (r^2 \Omega)$$

⇒ 

$$-\omega (+k_\perp^2 \tilde{\phi}_{k,\omega}) = -2\Omega i k_z \tilde{V}_{\theta k,\omega}$$

$$-\omega \tilde{V}_{\theta k,\omega} = -i k_z \frac{1}{r} \frac{\partial}{\partial r} (r^2 \Omega) \tilde{\phi}_{k,\omega}$$

$$k^2 = k_z^2 + k_r^2$$

$$\omega^2 k_z^2 = k_z^2 \frac{2\Omega}{r} \frac{d}{dr} (r^2 \Omega)$$

$$\omega^2 = \frac{k_z^2}{k^2} \Phi, \quad \Phi = \frac{2\Omega}{r} \frac{d}{dr} (r^2 \Omega)$$

Coaxial Flow?  
 Radial Buoyancy wave  
 Dispersion Relation

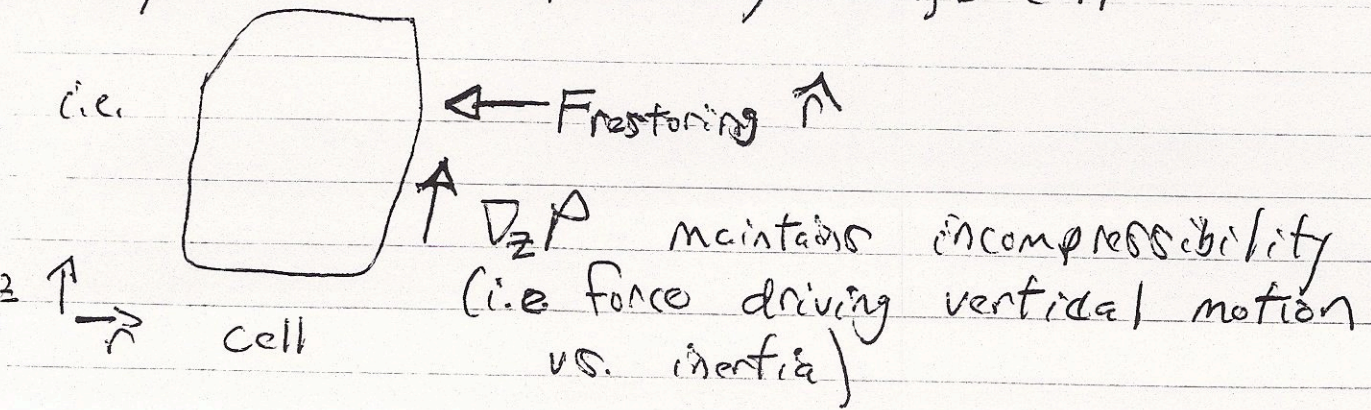
Rayleigh Discriminant  
 $\Phi > 0, (r^2 \Omega)' > 0 \rightarrow$  stable  
 $\Phi < 0, (r^2 \Omega)' < 0 \rightarrow$  unstable  
 (Rayleigh criterion)

Observe:

- Buoyancy wave:  $\omega^2 = \frac{k_z^2}{k^2} \Omega^2 \rightarrow$  Frequency is epicyclic, with  $k_z^2/k^2$  factor

i.e. epicyclic frequency appears in continuum picture as ~ buoyancy wave frequency (clear analogy to small oscillation frequency of particle)

$k_z^2/k^2 \Rightarrow$  incompressibility of  $r, z$  cell



• for long, thin cells, takes longer for vertical motion to maintain  $\underline{v} \cdot \underline{v} = 0 \Rightarrow$  frequency must drop with  $k_z \Rightarrow k_z^2/k^2$

(Preview:  $k_\theta = 0$  dens. wave:  $\omega^2 = \Phi + k_r^2 c_s^2 - 2\pi G \sigma |k_r|$ )

-  $\omega \rightarrow \omega + i\eta k^2$  recovers Taylor # criterion for  $R^2 < 0$  instability

$\Rightarrow$  Relation to Cort Parameters A, B:

Cort constants give local speed curve via local measurement of stellar motion

$$A = \frac{1}{2} \left( \frac{v_c}{r} - \frac{dv_c}{dr} \right) \equiv \begin{cases} \text{measure of net shear} \\ \text{on galactic motion (locally)} \end{cases}$$

$$= -\frac{1}{2} \left( r \frac{\partial \Omega}{\partial r} \right)_{R_0} \text{ shear}$$

$$V = \Omega_0 r, \text{ etc solid body} \Rightarrow A = 0$$

$\downarrow$   
const.

$$B = -\frac{1}{2} \left( \frac{v_c}{r} + \frac{dv_c}{dr} \right) = -\frac{1}{2r} \frac{d}{dr} (r v_c) \equiv \begin{cases} \text{angular momentum} \\ \text{gradient local} \end{cases}$$

$$= -\left( \frac{1}{2} r \frac{\partial \Omega}{\partial r} + \Omega \right) \text{ vorticity}$$

$$\text{since } R^2 = \left( R \frac{\partial \Omega^2}{\partial r} + 4\Omega^2 \right)_{R_0}$$

$$\Rightarrow R^2 = -4B(A-B) = -4B\Omega$$

$$\Omega(R_0) = A - B$$



### -- Physical Picture of Epicyclic Orbits

- epicycle is radial (in-and-out) oscillation (of star within disk; executing quasi-circular orbit) concurrent with orbit about galactic center

i.e. for sun  $\frac{R}{\Omega_0} = 2 \left( \frac{-B}{A-B} \right)^{1/2} \approx 1.3$ , for sun

- clearly, azimuthal oscillation accompanies radial i.e.

$$m r^2 \dot{\phi} = L_z$$

↓  
C.O.M.

Notes: in  $z=0$  plane, problem equivalent to planetary orbit

$$r^2 = (r_0 + x)^2 + z^2$$

in disk plane ( $z$  harmonic oscillation) for  $z \leq 300 \text{ pc}$ .

$$\Rightarrow \dot{\phi} = L_z / m (r_0 + x)^2 = L_z / m r_0^2 (1 + x/r_0)^2$$
$$\approx \frac{L_z}{m r_0^2} \left( 1 - \frac{2x}{r_0} + \dots \right)$$

but  $x = x_0 \cos(Kt + \alpha)$

$$\left\{ \begin{aligned} \phi &= \frac{L_z}{m r_0^2} \left( t - \frac{2x_0 \sin(Kt + \alpha)}{r_0 K} \right) + \phi_0 \\ &= \Omega_0 \left( t - 2x_0 / r_0 K \sin(Kt + \alpha) \right) + \phi_0 \\ r &= r_0 + x_0 \cos(Kt + \alpha) \end{aligned} \right.$$

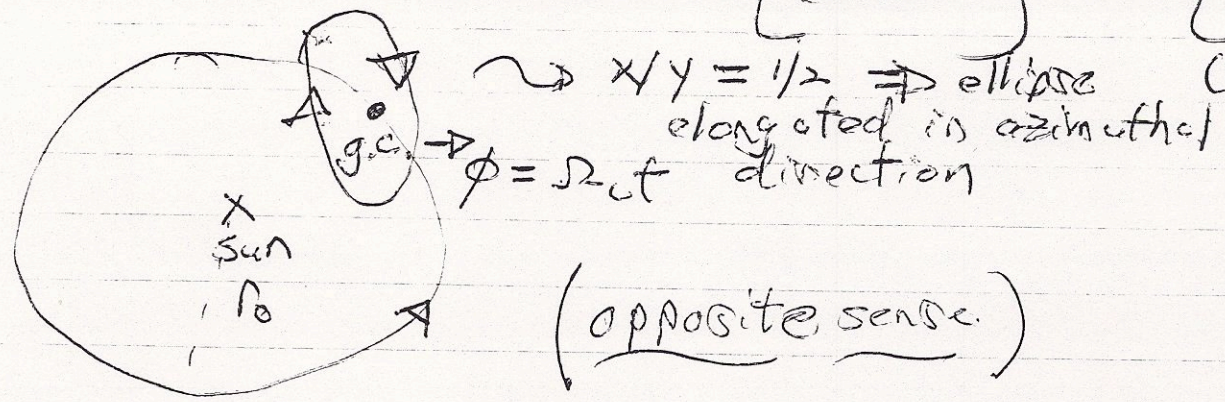
guiding center' (epicenter)  $\left\{ \begin{array}{l} r = r_0 \\ \phi = \Omega_0 t + \phi_0 \end{array} \right\} \rightarrow$  i.e.  $\left\{ \begin{array}{l} \text{circular} \\ \text{orbit} \end{array} \right\}$

Now, note (residual) epicyclic motion elliptical:

$$\begin{cases} x = x_0 \cos(Kt + \alpha) \\ y = r_0(\phi - \Omega_0 t) = -\frac{2x_0\Omega_0}{K} \sin(Kt + \alpha) \end{cases}$$

$\frac{x}{y} = \frac{K}{2\Omega_0}$  ; motion is retrograde (i.e.  $y \sim -x \sin(Kt + \alpha)$ )  
 $\frac{x}{y} = \frac{1}{2}$  For Kepler (i.e. sun + planet)  
 (semi-axis ratio)

Thus, net motion of planet =  $\left\{ \begin{array}{l} \text{circle of} \\ \text{guiding} \\ \text{center} \end{array} \right\} + \left\{ \begin{array}{l} \text{ellipse} \\ \text{of} \\ \text{epicycle} \end{array} \right\}$  (retrograde)



i.e. elliptical Kepler orbit  $\approx \left\{ \begin{array}{l} \text{prograde} \\ \text{circular} \\ \text{guiding center} \end{array} \right\} +$

$\left\{ \begin{array}{l} \text{retrograde epicyclic ellipse} \\ \text{(elongated tangentially)} \end{array} \right\}$

- Rev
- why 3rd
- Assum - low

# D.B.) Problem of the "Third Integral"

→ Recall, have been discussing  $V = V(r, z)$  potentials, and have  $(E/m) = \text{const}$

$$E = \frac{1}{2}(\dot{r}^2 + \dot{z}^2) + \frac{L_z^2}{2r^2} + V(r, z)$$

so clearly have Hamiltonian:

$$H = \frac{1}{2}(p_r^2 + p_z^2) + \frac{L_z^2}{2r^2} + V(r, z)$$

trivial  
 $E, L_z \rightarrow \text{constants}$   
 but  $U = U(r, z)$ ?  
 $\circ$  if  $U = U(r, z) \neq U(z)$   
 $\neq H_0$   
 3rd integral  $\rightarrow$   
 $E_z, \text{ see } E_r, E_z$   
 $\circ$  sphere  $L^2, L^1$

star stellar motion clearly has 2 integrals of motion  $E, L_z$ , at least 0

→ But, have observation:

→ stellar velocities in meridian plane  $(r, z)$  have preferred distribution (obs.)

→ if  $E, L_z$  are only I.O.M.'s,  $f(v_r, v_z, r)$  should be uniform in meridian plane, as  $f = f(\text{I.O.M.'s})$  only! - a contradiction!!  
 (n.b. i time scale -) d.e. ergodicity

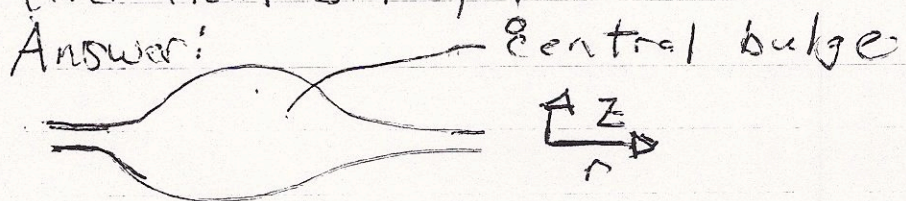
→ there must exist a THIRD I.O.M. in addition to  $L_z, E$ !!! → an why not uniform?

The Problem: How relate (3<sup>rd</sup> integral) to  $P_z, P_z, r, z$  etc.  $\rightarrow$  i.e. what is it? if it is...

$\Rightarrow$  { Henon-Helles Potential  
{ Program of Contopoulos, et. al

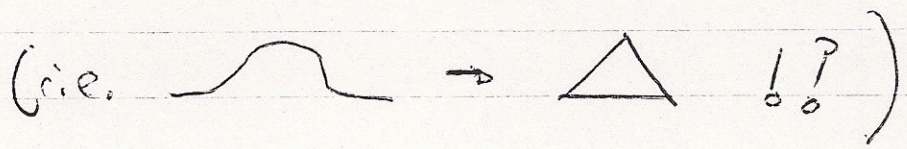
### 1.) Henon-Helles Potential

$\rightarrow$  What does a galaxy look like, meridionally (i.e. from side)?



$\rightarrow$   $V$  must have hard inner wall  $\rightarrow$  centrifugal <sup>eff</sup> potential; but stars must escape at large distance ( $F \sim GMm/r^2$  !)

H-H potential:  $V = \text{const.}$  along sides of equilateral triangle (symmetry  $\leftrightarrow$  simplicity)



( $r, z \rightarrow x, y$ )

so,

$$V(x, y) = (y + 1/2) \left( x^2 - \frac{(y-1)^2}{3} \right)$$

$= 0$  for  $\begin{cases} y = -1/2 \\ x = (y-1)/\sqrt{3} \\ x = -(y-1)/\sqrt{3} \end{cases}$

const.  
↓

$$V(x, y) = \frac{x^2 + y^2}{2} + x^2 y - \frac{y^3}{3} - \frac{1}{6}$$

so H-H Hamiltonian given by:

$$H = \frac{p_x^2 + p_y^2}{2m} + \frac{m\omega^2}{2}(x^2 + y^2) + \lambda \left( x^2 y - \frac{y^3}{3} \right)$$

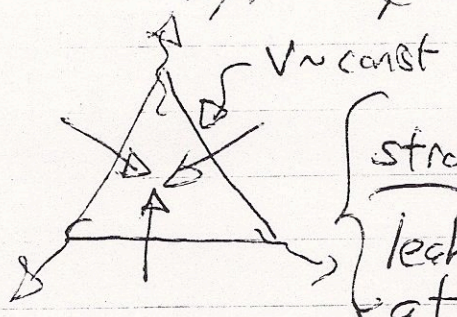
where:  $\lambda = m\omega^2/a$   
 ↓  
 some length (shape related)  
 $\left. \begin{matrix} m \\ \omega \\ a = m\omega^2/\lambda \end{matrix} \right\} \begin{matrix} 3 \\ \text{const.} \\ \text{of} \\ \text{phys.} \\ \text{system.} \end{matrix}$

observe:

- spherical symmetry → no length scale in V

⇒ meridional structure → V must contain scale info. → origin of  $\lambda$  ...

$$- V(x, y) = (y + 1/2) \left( x^2 - (y-1)^2/3 \right)$$



strong attraction  $\perp$  equilateral sides  
 leakage possible due weak attraction -  
 at corners (i.e.  $V < 0$  at  $x=0$ )

⇒ consistent with meridional asymmetry.

## In Search of the Third Invariant:

→ What do Orbits in H-H Potential look like? (are { - clues  
- approximate invariant

- Surface of Section Description

Have 4D system  $\{p_x, p_y, x, y\}$  ⇒ too difficult to visualize!

∴ try depict reduced phase space ⇔ exploit IOM's

-  $E(p_z, \dot{z}, r, \dot{r}) = \text{const.}$  ⇒ plot  $r, z, \dot{r}$   
(eliminating  $\dot{z}$  via  $E$ )  
→ still too difficult to visualize

- plot  $r, \dot{r}$  coordinates (2D phase space - all we can draw!) of star/particle crossing  $z = \text{const} = 0$  plane.

- remove  $\dot{z}$  ambiguity from plot via  $\dot{z} > 0$ , only plotted

∴ "Surface of section" ≡  $\dot{z} > 0$  trajectory "puncture plot" of  $r, \dot{r}$  plane, for  $z = 0$

⇒ reduces 4D representation to 2D

⇒ can vary  $z = \text{const.}$  → "different surfaces of section"

→ Using Surface of Section

- choose :  $x = 0$  } for surface of section  
 (symmetry of triangle!)
- plot :  $\dot{x} \geq 0$  crossings, only

for  $E$ , given

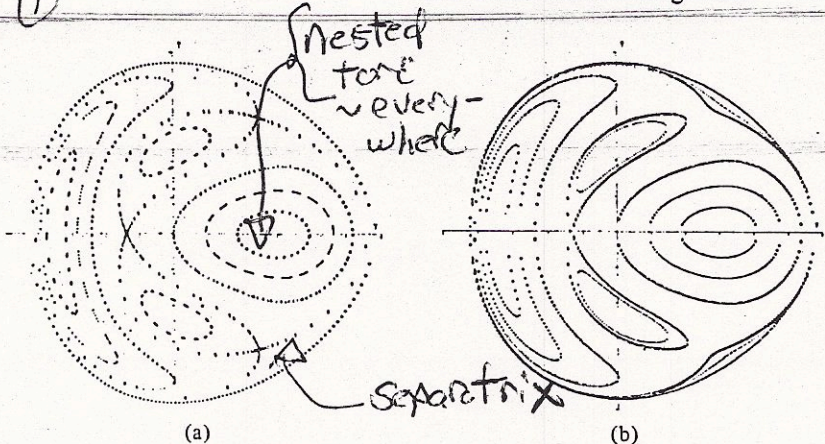
⇒ puncture points have  $\sum_{i=1}^2 p_{y_i}^2 + V(y_i) < E$ ,  
 which specifies domain of surface of section  
 (ACE) (boundary)

- initial point arbitrary ⇒ subsequent  
 $P_0 = (p_{y_0}, y_0)$   
 $P_1 = (p_{y_1}, y_1)$   
 $P_2 = (p_{y_2}, y_2)$   
 $\vdots$   
 $\vdots$   
 $\vdots$

with  $x=0, \dot{x} > 0$ .

- result : qualitatively, either
  - ⇒ puncture points line up on smooth curve  
 ⇒ trajectory on torus within energy surface  
 ⇒ "3<sup>rd</sup> invariant"  
 or
  - ⇒ puncture points not accommodated on smooth curve  
 ⇒ no invariant torus  
 ⇒ no additional invariant

①

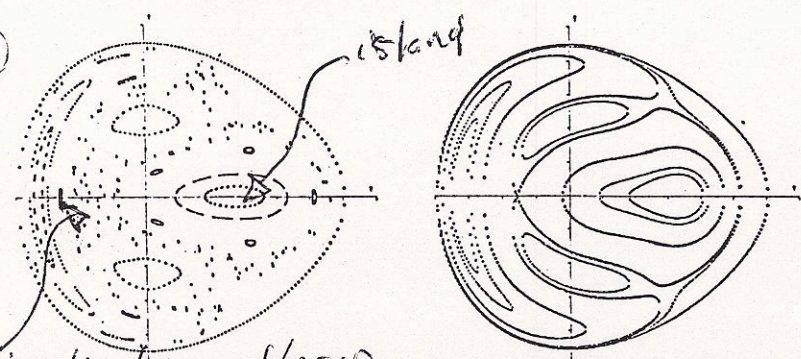


$E = 1/12$

lines shape indicate same trajectory

Figures 12a and 12b Surfaces of section for the Hénon-Heiles potential at the energy  $1/12$ , from numerical integration (a), and from Birkhoff-Gustavson renormalization (b) [from Gustavson (1966)].

②

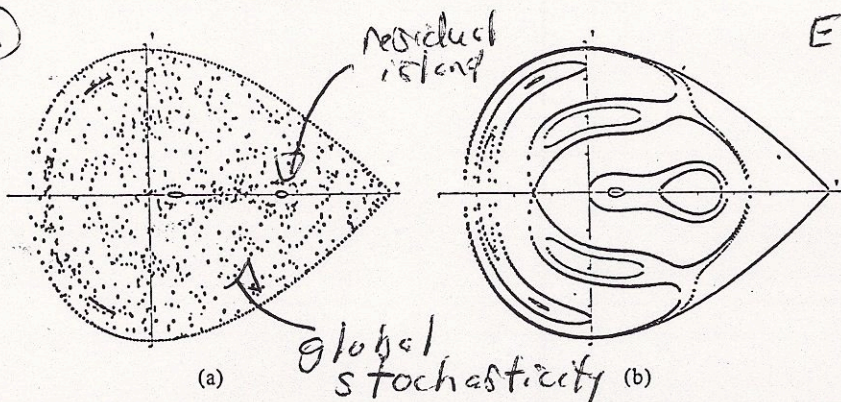


$E = 1/8$

stochasticity at/near x-point → connection/wandering (b) three tori

Figures 13a and 13b Same as preceding figure for the energy  $1/8$ .

③



$E = 1/6$

Figures 14a and 14b Same as preceding two figures for the escape energy  $1/6$ .

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Note:

→

① - nested tori  $\odot$  everywhere  $\Rightarrow$  nearly integrable,  
with approximate 3<sup>rd</sup> IOM

- separatrix evident  $\rightarrow$  old vibration-libration  
boundary for pendulum

- separatrix intersects self  $\Rightarrow$  x-point

$E = 1/2$   $\ll$   $E_{\text{escape}}$  from center of triangle

② - ergodicity evident  $\Rightarrow$  scatter of single trajectory  
evident!

- ergodicity starts at x-points (basins meet  
mountains)

- islands (remaining closed loops) correspond to tori  
in ①

③ - global stochasticity, albeit only  $y=1, \dot{y}=0$   
can escape

- tiny residual islands

$\rightarrow$  H-H system is equivalent to truncated  
Toda lattice, which is non-integrable.

observe:

For Keplerian orbit:  $r\Omega^2 = \frac{GM}{r^2}$

$$\Omega = \Omega_0 (r_0/r)^{3/2}$$

$$R^2 = \frac{2\Omega}{r} (r^3\Omega) = \Omega^2$$

⇒

$$R^2 / \Omega^2 = 1$$

- 1 epicycle per year, for earth!



→ what's the Implication for Galaxy?

- stellar motion in  $V(R, Z)$  likely non-integrable, possibly stochastic (depends on parameters)

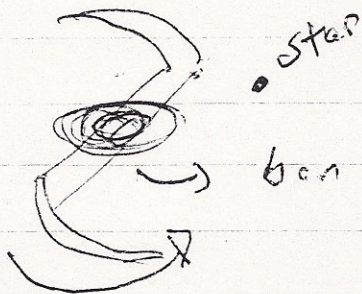
- escape from Galaxy possible

⇒ integration of Vlasov eqn.  $\rightarrow$  resonance broadening

c.) Rotating Potential - Bars, etc.  $\left\{ \begin{array}{l} \text{Co-rotation} \\ \text{Lineblad} \end{array} \right.$  Resonances.

in general, galaxies  $\left\{ \begin{array}{l} \text{rotate} \\ \text{can} \\ \text{non-axisymmetric} \end{array} \right.$

bar barred galaxies (B.T. Pg. 400)



clearly non-axisymmetric structure

where bar/spiral structure rotates,

- thus, individual star 'feels' time dependent, non-axisymmetric potential

- what happens?  $\rightarrow$  new frequency appears, namely  $\Omega_b$  - (bar) rotation frequency

orbit  
symmetry

3rd order

Ham

(1)

$$- \frac{d}{dr} (r d\Omega^2 + 4\Omega^2) = \frac{2r\Omega d\Omega + 4\Omega^2}{dr}$$

$$= \frac{2\Omega}{r} \frac{d}{dr} (r^2 \Omega)$$

$$= \frac{2\Omega}{r} (2r\Omega + r^2 \frac{d\Omega}{dr})$$

$$= 4\Omega^2 + 2r \frac{d}{dr} (\Omega^2)$$

(A) Sec. Motion

(B) Bos - Lyapunov

(C) Topology

(D)

asymptotically - flat

- Lyapunov

- Co-rotation

$$m(\Omega_{\text{rot}} - \Omega_{\text{orb}}) = \pm \frac{1}{2}$$

residual  $\rightarrow$

Co-rotation - closes - trajectory

static <sup>from</sup> ~~orbit~~ pt. - Ly

- lack of logarithmic divergence

$$\delta \phi_{\text{Ly}} = 0$$

- stable study

- orbits trapped

Jz checked

(3 table)

they

- time eq.

$$\text{E} \quad \text{E} ?$$

Varens effect

Donkey Effect

how do stars respond to tangential force

- sheep  $\rightarrow$  just drop (vertical)

- donkey  $\rightarrow$  resist  $\rightarrow$  it pulled/pushed stands, etc.

$$\phi = \frac{d\Omega}{dr} r = \frac{d}{dr} (r^2 \Omega)$$

$$= \frac{2r^2 \Omega + r^2 \frac{d\Omega}{dr}}{2M} = \frac{2r^2 \Omega + r^2 \frac{d\Omega}{dr}}{2M}$$

$$L = r^2 \Omega$$

$$\dot{L} = (2r\Omega + r^2 \frac{d\Omega}{dr}) \dot{r}$$

$$\dot{L} = r \frac{\dot{r}}{M}$$

$$\frac{r \dot{r}}{M} = (2r\Omega + r^2 \frac{d\Omega}{dr}) \dot{r}$$

$$A = -\frac{1}{2} r d^2 \psi / dr > 0$$

$$B = -\left( \Omega + \frac{1}{2} r \frac{d\Omega}{dr} \right) < 0$$

0000

⑦

$$\ddot{\phi} = \frac{-\Omega' F}{2m \left[ -\left( \Omega + \frac{r\Omega'}{2} \right) \right]}$$

with

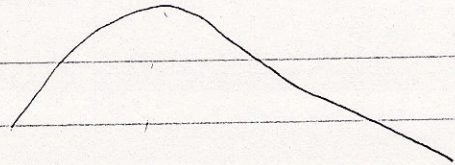
$$= \frac{A}{2m\Omega B} F$$

$$\ddot{\phi} = \frac{A}{2m\Omega B} F$$

$$\frac{A}{B} = \frac{\frac{1}{2} r d^2 \psi / dr}{\Omega + \frac{1}{2} r \frac{d\Omega}{dr}}$$

< 0  
 $\Omega \sim 1/r^2$

$$= \frac{1}{2} \frac{\psi''(-x)}{1/\Omega + \frac{1}{2}(-x)}$$



$$\alpha < 2$$

$\alpha > 2 \Rightarrow$  unstable

$$\int_{-\infty}^{\infty} (\psi^2)' > 0$$

$$\ddot{\phi} = -\frac{1}{m} F$$

decelerates  $\Rightarrow$

stable equilibrium pt.

of negative inertial mass.

Maximum of  $\phi$  at.

$F_+$   $\rightarrow$  decel.  $\Rightarrow$  stable

$F_-$   $\rightarrow$  accel  $\Rightarrow$  stable

$\phi$   $\cap$   $\rightarrow$  stable pt.

Donkey Effect

→ L-B i starts as donkeys  
 i.e. if pulled → slow  
 slowed → accelerate

Now, consider  $\int$  angular acceleration  
 } tangential force

$$\tau = \frac{dL}{dt} = Fr$$

$$\dot{\phi} = \frac{d\Omega}{dr} r^2 = -2A \frac{r^2}{r}$$

$$\begin{aligned} \text{but } \dot{r} &= \frac{dL}{dt} \\ &= \frac{(Fr)}{m} dr/dL \end{aligned}$$

$$\begin{aligned} L &= \Omega^2 r \\ dl/dr &= 2\Omega r \dot{\Omega} + \Omega^2 \\ &= -2\Omega B \end{aligned}$$

$$\dot{r} = \frac{Fr}{m} (-2\Omega B)^{-1}$$

$$r\ddot{\phi} = \frac{AF}{mB}$$

$$\begin{cases} A = \frac{-7}{2} r d\Omega/dt \\ B = -\Omega - \frac{7}{2} r d\Omega/dr \end{cases}$$

$$B \rightarrow ? \quad \Omega \sim r^{-\alpha} \quad (\alpha \sim 1)$$

$$B = -\underline{c} r^{-\alpha} + \frac{7}{2} c \alpha r^{-\alpha} \\ = -\Omega [1 - 11/2]$$

$$A = \frac{-7}{2} r \frac{d\Omega}{dr} = \frac{c \alpha}{2} r^{-\alpha}$$

$$r\ddot{\phi} = AF/mB = \frac{F}{m} \left[ \frac{\alpha/2}{1 - \alpha/2} \right]$$

$\alpha < 2 \Rightarrow \text{Mass} < 0$

$\rightarrow$  donkey

Point: Donkey at  $\phi_{max} \rightarrow$  stable!

$$\Rightarrow \ddot{r}_1 + \left( \frac{\partial^2 \bar{\Phi}_0}{\partial r^2} - \Omega_c^2 \right)_{r_0} r_1 - 2r_0 \Omega_c \dot{\phi}_1$$

$$= - \left( \frac{\partial \bar{\Phi}_0}{\partial r} \right)_{r_0} \cos(m(\Omega_c - \Omega_b)t)$$

$$\dot{\phi}_1 + 2\Omega_c \frac{\dot{r}_1}{r_0} = \frac{m \bar{\Phi}_0'(r_0)}{r_0^2} \sin[m(\Omega_c - \Omega_b)t]$$

$\Rightarrow$  now, integrate  $\phi_1$  equation:

$$\dot{\phi}_1 = -2\Omega_c \frac{\dot{r}_1}{r_0} - \frac{\bar{\Phi}_0'(r_0)}{r_0^2(\Omega_c - \Omega_b)} \cos[m(\Omega_c - \Omega_b)t]$$

and plug into  $r_1$  equation  $\Rightarrow$

$$\left\{ \begin{aligned} \ddot{r}_1 + K_0^2 r_1 &= \left[ - \frac{\partial \bar{\Phi}_0}{\partial r} + \frac{2\Omega_c \bar{\Phi}_0'}{r(\Omega_c - \Omega_b)} \right]_{r_0} \cos[m(\Omega_c - \Omega_b)t] \\ K_0^2 &\equiv \left( \frac{d^2 \Omega_c^2}{dr^2} + 4\Omega_c^2 \right)_{r_0} \end{aligned} \right.$$

clearly, resonance if  $m(\Omega_c - \Omega_b) = \pm K_0 \rightarrow$  Lindblad resonance

$\Omega_c = \Omega_b \rightarrow$  corotation resonance.



## Discussion of Resonances:

→ observe, in general, circular orbit has two 'natural frequencies', i.e.

- radial displacement:  $R_0$

- azimuthal displacement:  $0$  (i.e. sudden  $\Delta\phi \rightarrow$  particles continues at  $\Omega_c - \Omega_b$ )

so can understand resonances as

$$\omega_{\text{forcing}} = m(\Omega_c - \Omega_b) = \omega_{\text{nat}} \begin{cases} \pm R_0 \rightarrow \text{lin/bkcd} \\ 0 \rightarrow \text{co-rotation} \end{cases}$$

→ physically,

-  $\Omega_c = \Omega_b \rightarrow$  corotation (defines co-rotation radius)  
 $\rightarrow$  guiding center rotates with potential

-  $m(\Omega_c - \Omega_b) = \pm R_0 \rightarrow$  lin/bkcd (defines lin/bkcd radius)

→ star encounters potential crosso at frequency co-inciding with frequency of natural oscillation

→  $+R_0 \rightarrow$  star overtakes potential (inner)

$-R_0 \rightarrow$  potential overtakes star (outer)

in hydrodynamic anal. (i.e. Couette flow)  
take  $m \neq 0$  but  $k_0 \ll k_r, k_z$

$\Rightarrow$   $\underbrace{\text{symmetry}} \Leftrightarrow m \neq 0$   
 $\downarrow$   
 $(\omega - m \Omega_b)^2 \approx k_z^2 \Phi / (k_r^2 + k_z^2)$

$\downarrow$   
 $\Omega_b \equiv$  fluid rotation speed (no "bar" here)

thus, for external vibration at  $\omega_0$

$\omega_0 = m \Omega_b \rightarrow$  co-rotation frequency resonance

$\omega_0 = m \Omega_b \pm \left( \frac{k_z^2 \Phi}{k_r^2 + k_z^2} \right)^{1/2} \rightarrow$  Lindblad resonance.  
 (~ collective mode frequency)

$\Rightarrow$  Near resonance?

Recall:

$$\ddot{\eta}_1 + k_0^2 \eta_1 = \left[ -\frac{\partial \Phi_b}{\partial r} + \frac{2 \Omega_0 \Phi_b}{r(\Omega_0 - \Omega_b)} \right] \cos[m(\Omega_0 - \Omega_b)t]$$

clearly,  $\rightarrow$  secularity occurs when  $\Omega_0 \rightarrow \Omega_0, \Omega_{\text{Lind}}$ .

$\rightarrow$  resolve? - how (P?) describe orbit.

① Resonances between  $\Omega_b$  and circular frequency  $\Omega_c$   
 i.e.  $\Omega_b = \Omega_c \rightarrow$  co-rotation resonance

② Resonance between harmonics of  $\Omega_c - \Omega_b$  and epicyclic frequency  $K$

i.e.  $m(\Omega_c - \Omega_b) = \pm K_0 \rightarrow$  Lindblad resonance

$\rightarrow$  Weak Bars - P.T.

- consider  $\underline{x}$  in frame rotating at  $\Omega_b$ , with  $\underline{\Omega}_b = \Omega_b \hat{z}$ , and  $r, \phi$  in plane  $\perp$

$$\frac{d}{dt} \Big|_{in} = \frac{d}{dt} \Big|_{frm} + \underline{\Omega}_b \times \quad \left\{ \begin{array}{l} \text{i.e. eliminate} \\ \text{time dependence} \\ \text{via frame change} \end{array} \right.$$

$$\underline{\text{So}} \quad \frac{d}{dt} \Big|_{frm} = \frac{d}{dt} \Big|_{in} - \underline{\Omega}_b \times$$

Now  $\underline{\ddot{r}}_{in} = -\underline{\nabla} \Phi$  Coriolis force. Cent. force

$$\underline{\text{So}} \quad \underline{\ddot{r}} = -\underline{\nabla} \Phi - 2(\underline{\Omega}_b \times \underline{\dot{r}}) - \underline{\Omega}_b \times (\underline{\Omega}_b \times \underline{r})$$

$$= -\underline{\nabla} \left( \Phi - \frac{1}{2} \Omega_b^2 r^2 \right) - 2(\underline{\Omega}_b \times \underline{\dot{r}})$$

Centrifugal potential

observe:

$$\underline{\ddot{r}} = -\underline{\nabla} \left( \Phi - \frac{\Omega_b^2}{2} r^2 \right) - 2 (\underline{\Omega}_b \times \underline{\dot{r}})$$

$$\underline{\dot{r}} \cdot \underline{\ddot{r}} = -\underline{\dot{r}} \cdot \underline{\nabla} \left( \Phi - \frac{\Omega_b^2}{2} r^2 \right)$$

- Coriolis force does no work
- can define effective potential

$$\Phi_{\text{eff}} = \Phi - \frac{1}{2} \Omega_b^2 r^2$$

$$\stackrel{\text{so}}{=} E_J = \frac{\dot{r}^2}{2} + \Phi_{\text{eff}} \quad ; \quad \frac{dE_J}{dt} = 0$$

↓  
Jacobi's integral  
(Energy with centrifugal potential)

- more generally:

$$E_J = \frac{\dot{r}^2}{2} + \Phi = \frac{1}{2} |\underline{\Omega}_b \times \underline{r}|^2$$

in  $r, \phi$  polar coordinates:

$$\ddot{r} - r\dot{\phi}^2 = -\frac{\partial \Phi}{\partial r} + 2r\Omega_b\dot{\phi} + \Omega_b^2 r$$

$$r\dot{\phi}'' + 2\dot{r}\dot{\phi} = -\frac{1}{r} \frac{\partial \Phi}{\partial \phi} - \underbrace{2\dot{r}\Omega_b}_{\text{pert}}$$

For weak bar,  $\Phi = \Phi_0(r) + \Phi_1(r, \phi)$

↓  
perturb about circular orbit

↗  $|\Phi_1/\Phi_0| \ll 1$ , small pert.

so, can write similarly:

$$r(t) = r_0 + r_1(t)$$

$$\phi(t) = \phi_0(t) + \phi_1(t)$$

$$\phi_0(t) = (\Omega_c - \Omega_b)t$$

so, lowest order:

$$\ddot{r}_1 - (r_0 + r_1)(\dot{\phi}_0 + \dot{\phi}_1)^2 = -\frac{\partial}{\partial r} (\Phi_0 + \Phi_1)$$

$$+ 2(r_0 + r_1)\Omega_b(\dot{\phi}_0 + \dot{\phi}_1) + \Omega_b^2(r_0 + r_1)$$

⇒

$$-r_0\dot{\phi}_0^2 = -\frac{\partial \Phi_0}{\partial r} + \Omega_b^2 r_0 + 2r_0\Omega_b\dot{\phi}_0$$

$$\Rightarrow \rho_0 (\dot{\phi}_0 + \Omega_b)^2 = \left( \frac{\partial \Phi_0}{\partial r} \right)_{r_0}$$

$\downarrow$   
 $\rho_0 \Omega_c^2$

$\left\{ \begin{array}{l} \text{defines circular} \\ \text{frequency} \end{array} \right.$

$\underbrace{\quad}_{\text{c.c.}}$  radial force balance

$$\Omega_c^2(r) = \frac{1}{r} \frac{\partial \Phi_0}{\partial r} \quad \checkmark$$

$$\dot{\phi}_0 = \Omega_c - \Omega_b$$

Similarly,  $\phi_0 = (\Omega_c - \Omega_b)t$       transform frame

First order:

$$\dot{\eta}_1 + \left( \frac{\partial^2 \Phi_0}{\partial r^2} - \Omega_c^2 \right) \eta_1 - 2\rho_0 \Omega_c \dot{\phi}_1 = - \frac{\partial \Phi_1}{\partial r} \Big|_{r_0}$$

$$\dot{\phi}_1 + 2\Omega_c \frac{\eta_1}{r_0} = \frac{1}{r_0^2} \frac{\partial \Phi_1}{\partial \phi} \Big|_{r_0}$$

To make progress:

- Fourier analyze  $\phi_1$ , i.e.

$$\Phi_1(r, \phi) = \bar{\Phi}_1(r) \cos m\phi$$

$$\phi = \phi_0 + \phi_1, \text{ assume } \phi_1 \ll \phi_0$$

$$\Rightarrow \cos(m\phi) \cong \cos(m\phi_0) = \cos(m(\Omega_c - \Omega_b)t)$$

exact

=> useful to consider Lagrange points and orbits near them.   
 non-part   
 co-rotation   
 i.e. fixed points of stationary field

Lagrange points  $\left\{ \begin{array}{l} \partial \Phi_{\text{eff}} / \partial x = 0 \\ \partial \Phi_{\text{eff}} / \partial y = 0 \end{array} \right.$  i.e. equilibrium/stationary points of effective potential.

i.e. at L.P.'s, star travels on circular orbit appearing stationary in rotating frames.  $\rightarrow$  co-rotation!

Now, consider in-plane (of disk) motion in elliptical potential (rotating) i.e.

$$\Phi_{\text{eff}}(x, y) = \left. \Phi_{\text{eff}}(x, y, z) \right|_{z=0} ; E = \frac{\dot{r}^2}{2} + \Phi_{\text{eff}}$$

$$= \Phi_L(x, y) - \Omega_0^2 r^2$$

$\rightarrow$  (2D Coulomb potential)

where

axisym  $\Phi_L(x, y) = \frac{1}{2} V_0^2 \ln \left( R_0^2 + x^2 + y^2 / \rho^2 \right)$  (2D)   
 core radius   
 inner cutoff   
 ellipsoid

$\rightarrow$  why  $\Phi_L(x, y)$ ?  $\Rightarrow$  simple non-axisymmetric example

- equipotentials have constant ratio  $\frac{r}{R_0} \Rightarrow$  non-axisymmetry similar at all radii (i.e. captures ellipsoidal shape)

inside

- for  $r \ll R_0 \Rightarrow$  expand, yielding

$$\Phi_L(x, y) \approx \frac{V_0^2}{2 R_0^2} (x^2 + y^2 / \rho^2)$$

all const. at.

ie.  $\Phi$  is 2D harmonic oscillator, generated by homogeneous ellipsoid  $\rightarrow R < R_0$ ,  $\Phi_L$  approximates homogeneous density distribution (ellipsoidal) potential

[homog. sphere  $\rho = \rho_0 \Rightarrow \ddot{r} = -\frac{d\phi}{dr} = F_r$

$-4\pi r^2 \frac{F}{r} = +\frac{4\pi G \rho_0}{3} r^3 \Rightarrow F_r = -\frac{G \rho_0}{3} r \Rightarrow \text{h.o.}$ ]

outside

$-R \gg R_0, \quad g \approx 1 \Rightarrow \Phi_L \approx V_0^2 \ln r$

$\Rightarrow \left\{ \begin{array}{l} V_0 \approx V_0(\ln(r))^{1/2} \sim \text{const.} \Rightarrow \\ \text{flat rotation curve often} \\ \text{observed!} \end{array} \right.$

$\rightarrow$  why Lagrange points interesting?  $\rightarrow$  Lagrange points are those where star travels on circular orbit, appearing stationary in rotating frame; ie.  $\frac{d\phi_{\text{eff}}}{dx} = 0, \quad \frac{d\phi_{\text{eff}}}{dy} = 0$

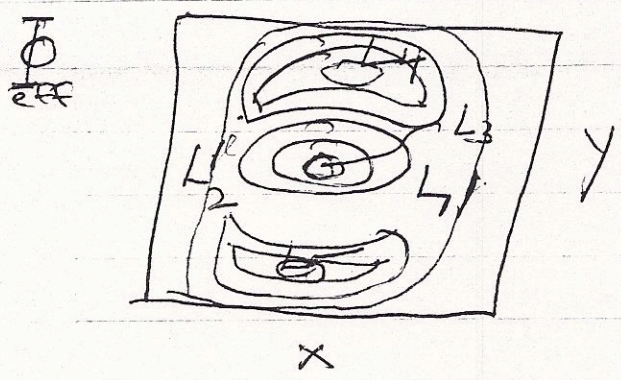
so at L.P.'s:

$\ddot{\underline{r}} = -2\underline{\Omega} \times \underline{\dot{r}}$ , i.e. only force is Coriolis  $\Delta \rightarrow$  precession.

i.e. clearly L.P.'s,  $\Delta \Rightarrow$  co-rotation.



-  $\rightarrow$  L.P.'s for  $\Phi_L(x, y)$



B. and T. Fig. 3-13  
 pg. 137  
 $v_0 = 1, \Omega = .8, R_0 = .1$   
 $\Omega_b = 1$

- $L_3 \rightarrow$  minima  $\Phi_{eff}$
- $L_4, L_5 \rightarrow$  maxima  $\Phi_{eff}$
- $L_1, L_2 \rightarrow$  saddle points  $\Phi_{eff}$

Donkey?

"Region of co-rotation"  $\equiv$   $L_1, L_2$  circle  
 $L_4, L_5$  circle.

$\rightarrow$  Motion Near L.P.'s?

Expand!  $\begin{cases} x = x_L + \epsilon \\ y = y_L + \eta \end{cases}$

$$\Phi_{eff}(x, y) = \Phi_{eff}(x_L, y_L) + \epsilon \frac{\partial \Phi_{eff}}{\partial x} \Big|_{x_L, y_L} + \eta \frac{\partial \Phi_{eff}}{\partial y} \Big|_{x_L, y_L}$$

$$+ \frac{\epsilon^2}{2} \frac{\partial^2 \Phi_{eff}}{\partial x^2} \Big|_{x_L, y_L} + \frac{\eta^2}{2} \frac{\partial^2 \Phi_{eff}}{\partial y^2} \Big|_{x_L, y_L}$$

$+ \epsilon \eta \frac{\partial^2 \Phi_{eff}}{\partial x \partial y} \Big|_{x_L, y_L}$  (symmetry  $\rightarrow$  isn't principal axis along coord. axis).

$$\Rightarrow \left. \begin{aligned} \ddot{\xi} &= 2\Omega_b \dot{\eta} - \phi_{xx} \xi \\ \ddot{\eta} &= -2\Omega_b \dot{\xi} - \phi_{yy} \eta \end{aligned} \right\} \text{equations of motion in vicinity of Lagrange Point}$$

For stability (i.e. will particle remain at Lagrange point)

$$\xi = x e^{\lambda t}, \eta = y e^{\lambda t}$$

$$\begin{aligned} \lambda^2 x &= 2\Omega_b \lambda y - \phi_{xx} x \\ \lambda^2 y &= -2\Omega_b \lambda x - \phi_{yy} y \end{aligned} \Rightarrow \det \begin{vmatrix} \lambda^2 + \phi_{xx} & -2\lambda y \Omega_b \\ 2\lambda x \Omega_b & \lambda^2 + \phi_{yy} \end{vmatrix} = 0$$

$$\lambda^4 + \lambda^2 (\phi_{xx} + \phi_{yy} + 4\Omega_b^2) + \phi_{xx} \phi_{yy} = 0$$

$$\lambda^2 = - \frac{(\phi_{xx} + \phi_{yy} + 4\Omega_b^2)}{2} \pm \frac{1}{2} \left[ (\phi_{xx} + \phi_{yy} + 4\Omega_b^2)^2 - 4\phi_{xx} \phi_{yy} \right]^{1/2}$$

Need  $\lambda^2 < 0$  for stability

Now, for  $\lambda^2$  real,  $\lambda^2 < 0 \Rightarrow$  stable L.P.'s :

$$\Rightarrow \begin{cases} \phi_{xx} \phi_{yy} > 0 \\ C > 2(\phi_{xx} \phi_{yy})^{1/2} \end{cases} \quad \begin{cases} C = \phi_{xx} + \phi_{yy} + 4\Omega_b^2 \end{cases}$$

Thus: d.e.  $\lambda_1^2, \lambda_2^2 > 0 \Rightarrow \phi_{xx} \phi_{yy} > 0$   
 $\lambda_1^2 + \lambda_2^2 < 0 \rightarrow -(\phi_{xx} + \phi_{yy} + 4\Omega_b^2) < 0$   
 $\lambda^2$  real  $\rightarrow C > 2\sqrt{\phi_{xx} \phi_{yy}}$

$\rightarrow$  at saddle points ( $L_1, L_2$ )  $\phi_{xx} \phi_{yy} < 0$  (i.e. opposite signs)  $\Rightarrow$  unstable

( )

↓

aside:  $\lambda^4 + \lambda^2 (\phi_{xx} + \phi_{yy} + 4\Omega b^2)$

stability  
of

Lagrange points  
for rotating  
bar model

$$+ \phi_{xx} \phi_{yy} = 0$$

$$\Rightarrow \lambda_1^2$$

$$\Rightarrow \lambda_2^2$$

stability

$$\left. \begin{array}{l} \lambda_1^2 \\ \lambda_2^2 \end{array} \right\} < 0$$

$$\lambda_{1,2}^2 = -\frac{C}{2} \pm \frac{1}{2} \left[ C^2 - 4\phi_{xx}\phi_{yy} \right]^{1/2}$$

conditions

$$\textcircled{1} \lambda_1^2 + \lambda_2^2 = -C < 0$$

sum < 0 if both < 0

$$\textcircled{2} \lambda_1^2 \lambda_2^2 > 0$$

requires both < 0

$$\Rightarrow \phi_{xx} \phi_{yy} > 0$$

$$\textcircled{3} \lambda^2 \text{ test } [ ]^{1/2} > 0$$

$$\begin{array}{l} L_1 \\ L_2 \end{array} \left. \vphantom{\begin{array}{l} L_1 \\ L_2 \end{array}} \right\} \text{saddle } \phi_{xx} \phi_{yy} < 0$$

→ unstable

$L_0$   $\xrightarrow{\text{trivial}}$  minimum  $\rightarrow$  stable, but trivial

$L_4$  }  $\rightarrow$  maximum  $\rightarrow$  stable modulo  
 $L_5$  } parameters

$L_4$  }  $\Rightarrow$  only potentially relevant  
 $L_5$  } Lagrange points.

- clearly, minima stable ( $L_3$ )

$\rightarrow L_4, L_5$  stable if exist and  $C > 2(\phi_{xx} \phi_{yy})^{1/2}$   
 i.e. quantitative question.  $\rightarrow$  help

$\rightarrow$  For picture of orbit:  
 have characteristic eqn:

$$\lambda^4 + \lambda^2(\phi_{xx} + \phi_{yy} + 4\Omega_b^2) + \phi_{xx}\phi_{yy} = 0$$

for stable orbits (near L.P.'s),  $\lambda^2 = -\alpha^2, -\beta^2$   
 $\alpha^2, \beta^2 > 0$  i.e.

$$\xi = X_1 \cos(\alpha t + \phi_1) + X_2 \cos(\beta t + \phi_2)$$

$$\eta = Y_1 \sin(\alpha t + \phi_1) + Y_2 \sin(\beta t + \phi_2)$$

where orbit eqns  $\Rightarrow$

$$(0 \leq \alpha \leq \beta \text{ real})$$

$$\begin{cases} Y_1 = \frac{\phi_{xx} - \alpha^2}{2\Omega_b \alpha} X_1 = \frac{2\Omega_b \alpha}{\phi_{yy} - \alpha^2} X_1 \\ Y_2 = \frac{\phi_{xx} - \beta^2}{2\Omega_b \beta} X_2 = \frac{2\Omega_b \beta}{\phi_{yy} - \beta^2} X_2 \end{cases}$$

c.e.

→ orbits near L.P.'s are superposition of elliptical motion at  $\omega = \alpha, \beta$

→ for:  $\Phi_{\text{eff}} = \frac{V_0^2}{2} \ln\left(R_0^2 + \frac{x^2 + y^2}{\Sigma^2}\right) - \frac{\Omega_b^2}{2} (x^2 + y^2)$

$e = (1 - \Sigma^2)^{1/2}$ , ( $\Sigma < 1$ )  $\equiv$  ellipticity

then:  $L_4, L_5$  at  $y_L = \left(\frac{V_0^2}{\Omega_b^2} - \Sigma^2 R_0^2\right)^{1/2}$

$\Rightarrow$  only get  $L_4, L_5$  if  $\begin{cases} R_0^2 < V_0^2 / \Sigma^2 \Omega_b^2 \\ \Omega_b^2 < V_0^2 / \Sigma^2 R_0^2 \end{cases}$

Now, crank  $\Rightarrow$

$\left. \frac{\partial^2 \Phi}{\partial x^2} \right|_{0, y_L} = -\Omega_b^2 (1 - \Sigma^2)$

$\left. \frac{\partial^2 \Phi}{\partial y^2} \right|_{0, y_L} = -2\Omega_b^2 \left(1 - \Sigma^2 \left(\frac{\Omega_b R_0}{V_0}\right)^2\right)$

$(\Phi_{xx} + \Phi_{yy} + 4\Omega_b^2) = \Omega_b^2 \left[1 + \Sigma^2 + 2\Sigma^2 \left(\frac{\Omega_b R_0}{V_0}\right)^2\right]$

c.e.  $\Phi_{xx} \Phi_{yy} > 0$  if L.P.'s exist.

→  
 for  $( ) > (\phi_{xx} \phi_{yy})^{1/2}$  (stability), if

(specific case)  $R_0 \rightarrow 0$ , so  $(\Omega_b R_0 / V_0)^2 \rightarrow 0$ , then

stability if  $2^2 \geq (.81)^2$ .

In this case:

$$\alpha = e^2 \Omega_b^2 = -\frac{\Phi}{I_{xx}}$$

$$\beta^2 = 2 \Omega_b^2$$

P

-  $\alpha$  ellipse elongated in  $x$  (tangential) direction

-  $\beta$  ellipse:  $y_2 = -x_2 / \sqrt{2}$  ( $\Rightarrow$  retrograde motion!)  
 $\beta^2 = 2 \Omega_b^2$

-  $\beta$  ellipse is (basically) epicyclic motion,  $w'$

-  $\alpha$  ellipse is slow slashing in non-axisymmetric  $\phi_L$ . (see 33)

## Co-rotation

D Now, near

resonance (original goal):

$$\ddot{r}_1 + \left( \frac{\partial^2 \Phi_0}{\partial r^2} - \Omega^2 \right) r_1 - 2\Omega_0 \Omega_c \dot{\phi}_1 = -\frac{\partial \Phi_1}{\partial r} / \Omega_0$$

$$\ddot{\phi}_1 + 2\Omega_0 \frac{\dot{r}_1}{r_0} = -\frac{1}{r_0^2} \frac{\partial \Phi_1}{\partial \phi} / \Omega_0$$

but!  $K^2 = \left( r \frac{\partial}{\partial r} \Omega^2 + 4\Omega^2 \right) \rightarrow$  epicyclic frequency

$$r \Omega^2 = \frac{\partial \Phi}{\partial r} \Rightarrow \frac{\partial}{\partial r} (r \Omega^2) = \frac{\partial^2 \Phi}{\partial r^2}$$

$$\frac{\partial}{\partial r} (r^2 \Omega) = 2r\Omega + r^2 \frac{\partial \Omega}{\partial r}$$

$$\frac{\partial}{\partial r} (r^2 \Omega^2) = 2r\Omega \frac{\partial \Omega}{\partial r} + 2r^2 \Omega \frac{\partial \Omega}{\partial r}$$

$$r \frac{\partial}{\partial r} (r \Omega^2) + 4\Omega^2 = \frac{\partial^2 \Phi}{\partial r^2}$$

so

$$\frac{\partial^2 \Phi}{\partial r^2} - \Omega^2 = r \frac{\partial}{\partial r} (r \Omega^2) = K^2 - 4\Omega^2$$

$$\Rightarrow \begin{cases} \textcircled{1} & \textcircled{2} & \textcircled{3} & \textcircled{4} \\ \ddot{r}_1 + (K_0^2 - 4\Omega_0^2) r_1 - 2\Omega_0 \Omega_c \dot{\phi}_1 = -\frac{\partial \Phi_1}{\partial r} \end{cases}$$

$$\left\{ \begin{aligned} \ddot{\phi}_1 + 2\Omega_0 \frac{\dot{r}_1}{r_0} &= -\frac{1}{r_0^2} \frac{\partial \Phi_1}{\partial \phi} \end{aligned} \right.$$

where  $\left\{ \begin{aligned} \Omega_0 &= \Omega_c(r_0) = \Omega_b \\ \phi_0 &= \pi/2 \end{aligned} \right\}$  L5 point

$r_0 \equiv$  co-rotation radius.

max



Ordering: ①  $\rightarrow e^3$   
 ②  $\rightarrow e$        $e \equiv$  ellipticity  
 ③  $\rightarrow e$   
 ④  $\rightarrow e^2$

e.g.  $\Phi_1 \sim e^2$ ,  $\eta_1 \sim e$       see 33a.  
 $\frac{d}{dt} \sim e$ ,  $\phi_1 \sim e^0$

$\Rightarrow$   $\eta_1$  equation  $\Rightarrow$

$$2r_0 \Omega_0 \dot{\phi}_1 = (K_0^2 - 4\Omega_0^2) \eta_1$$

$$\Rightarrow \eta_1 = \frac{2r_0 \Omega_0 \dot{\phi}_1}{(K_0^2 - 4\Omega_0^2)}$$

$$\dot{\phi}_1 + \frac{4\Omega_0^2}{K_0^2 - 4\Omega_0^2} \dot{\phi}_1 = -\frac{1}{r_0^2} \frac{\partial \Phi_1}{\partial \phi} \Big|_{\phi_0 + \phi_1}$$

$$\left\{ \frac{K_0^2}{K_0^2 - 4\Omega_0^2} \dot{\phi}_1 = -\frac{1}{r_0^2} \frac{\partial \Phi_1}{\partial \phi} \Big|_{\phi_0 + \phi_1} \right. \quad \left( \Phi_1 = \Phi_0(r) \cos(2\phi) \right)$$

taking  $m=2$  (symmetric bar)  $\Rightarrow$

$$\dot{\phi}_1 = -\frac{2\Phi_0}{r_0^2} \frac{(4\Omega_0^2 - K_0^2)}{K_0^2} \sin[2(\phi_0 + \phi_1)]$$

2: Ordering

$$\Phi_1 \sim e^2 \Rightarrow \text{weak non-axisymmetry}$$

$\leftrightarrow$  assumption

Recall, for L.P. oscillation,

$$\alpha^2 = e^2 \Omega_b^2 \Rightarrow \frac{d}{dt} \sim e$$

$\times$  ellipse tangential  $\Rightarrow$

$$\begin{aligned} \eta_1 &\sim e \\ \phi_1 &\sim e^0 \end{aligned}$$

this

Now,  $\left\{ \begin{array}{l} \alpha^2 = \frac{4|\Phi|}{r_0^2} \frac{(4\Omega_0^2 - \kappa_0^2)}{\kappa_0^2} \\ \psi = 2(\phi_0 + \phi_1) \end{array} \right\}$  related to strength of trapping near co-rotation.

$\Rightarrow \frac{d^2\psi}{dt^2} = -\alpha^2 \sin \psi \Rightarrow$  pendulum!

$$E_\psi = \frac{1}{2} \left( \frac{d\psi}{dt} \right)^2 - \alpha^2 \cos \psi$$

$$= \frac{1}{2} \dot{\psi}^2 + V, \quad V = -\alpha^2 \cos \psi$$

Now:

$\rightarrow$  observe  $\psi = 2(\phi_0 + \phi_1)$ ,  $\phi_1 = 0$  is maximum  $V$   
 $= 2\left(\frac{\pi}{2} + \phi_1\right)$

$\rightarrow E_\psi < \frac{\alpha^2}{2} \rightarrow$  trapped motion (libration) at/around Lagrange point

$E_\psi > \frac{\alpha^2}{2} \rightarrow$  rotation/circulation about galactic center

$\rightarrow$  For orbit curves, have

$$r_1 = 2r_0 \Omega_0 \phi_1^0 / (\kappa_0^2 - 4\Omega_0^2)$$

$$\text{out } \frac{1}{2} \dot{\phi}_1^2 = E_\psi + \frac{p^2}{2} \cos \psi$$

$$\Rightarrow \eta_1 = \pm \left( \frac{I_0 \Omega_c}{4\Omega_c^2 - k_0^2} \right) \left( 2 \left( E_\psi + \frac{p^2}{2} \cos (2\phi_1) \right) \right)^{1/2}$$

→ Contrast:

- previous analysis: valid for small oscillation about L.P. of arbitrary 2D rotating potential
- here, analysis for any amplitude excursion about L<sub>4</sub>, L<sub>5</sub> points of weakly non-axisymm. potential.